

Vektoridentitäten 1.1

$$\begin{aligned} \bullet \quad \underline{a \cdot (b \wedge c)}_i &= a_i \cdot (b \wedge c)_i = a_i \varepsilon_{ijk} b_j c_k \\ &= -\varepsilon_{ikj} a_i b_j c_k = b_j \varepsilon_{kji} c_k a_i = b \cdot (c \wedge a) \end{aligned}$$

analog für $c \cdot (a \wedge b)$

$$\begin{aligned} \bullet \quad \underline{(a \wedge (b \wedge c))}_i &= \varepsilon_{ijk} a_j (b \wedge c)_k = \varepsilon_{ijk} a_j \varepsilon_{klm} b_l c_m \\ &= a_j \varepsilon_{ijk} \varepsilon_{klm} b_l c_m = a_j \varepsilon_{kij} \varepsilon_{klm} b_l c_m = \\ &= a_j \delta_{ie} \delta_{jm} b_l c_m - a_j \delta_{im} \delta_{je} b_l c_m = (a_j \cdot c_j) \cdot b_i - (a_j \cdot b_j) \cdot c_i \\ &= (a \cdot c) b - (a \cdot b) c \end{aligned}$$

$$\begin{aligned} \bullet \quad \underline{(a \wedge b) \cdot (c \wedge d)} &= \varepsilon_{ijk} a_j b_k \cdot \varepsilon_{imn} c_m d_n \\ &= a_j b_k (\delta_{jm} \delta_{kn} - \delta_{jn} \delta_{km}) c_m d_n = a_j b_k c_j d_k - a_j b_k c_k d_j \\ &= (a \cdot c)(b \cdot d) - (a \cdot d)(b \cdot c) \end{aligned}$$

$$\underline{(\operatorname{rot} \operatorname{grad} \psi)_i} = \varepsilon_{ijk} \partial_j \partial_k \psi \quad (\partial_j := \frac{\partial}{\partial x_j})$$

$$= \sum_{\substack{\sigma \in S_3 \\ \sigma(1)=i}} \varepsilon_{\sigma(1)\sigma(2)\sigma(3)} \partial_{\sigma(2)} \partial_{\sigma(3)} \psi$$

$$= \sum_{\substack{\sigma \in S_3 \\ \sigma(1)=i \\ \sigma \text{ gerade}}} \varepsilon_{\sigma(1)\sigma(2)\sigma(3)} \partial_{\sigma(2)} \partial_{\sigma(3)} \psi + \varepsilon_{\sigma(1)\sigma(3)\sigma(2)} \partial_{\sigma(3)} \partial_{\sigma(2)} \psi$$

$$= \sum_{\substack{\sigma \in S_3 \\ \sigma(1)=i \\ \sigma \text{ gerade}}} \underbrace{\varepsilon_{\sigma(1)\sigma(2)\sigma(3)} \partial_{\sigma(2)} \partial_{\sigma(3)} \psi - \varepsilon_{\sigma(1)\sigma(2)\sigma(3)} \partial_{\sigma(3)} \partial_{\sigma(2)} \psi}_{= 0}$$

$$= 0$$

$$\underline{\operatorname{div} \operatorname{rot} A}_i = \partial_i \varepsilon_{ijk} \partial_j A_k = \varepsilon_{ijk} \partial_i \partial_j A_k = \varepsilon_{kij} \partial_i \partial_j A_k = 0$$

(siehe oben)

$$\begin{aligned} \underline{\operatorname{rot}(\operatorname{rot} A)}_i &= \varepsilon_{ijk} \partial_j (\operatorname{rot} A)_k = \varepsilon_{ijk} \partial_j \varepsilon_{kmn} \partial_m A_n = \varepsilon_{kij} \varepsilon_{kmn} \partial_j \partial_m A_n \\ &= (\delta_{im} \delta_{jn} - \delta_{in} \delta_{jm}) \partial_j \partial_m A_n = \delta_{im} \delta_j \partial_m A_j - \delta_{in} \partial_j^2 A_n \\ &= \partial_i \partial_j A_j - \partial_j^2 A_i = \operatorname{grad}(\operatorname{div} \vec{A}) - \Delta \vec{A} \end{aligned}$$

$$\cdot \quad \underline{\text{div}(\psi \vec{A})} = \partial_i (\psi A_i) = \partial_i \psi \cdot A_i + \psi \partial_i A_i = \vec{A} \cdot \nabla \psi + \psi \text{div} \vec{A}$$

$$\begin{aligned} \cdot \quad \underline{\text{rot}(\psi \vec{A})}_i &= \epsilon_{ijk} \partial_j (\psi A_k) = \epsilon_{ijk} (\partial_j \psi) A_k + \epsilon_{ijk} \psi \partial_j A_k \\ &= \epsilon_{ijk} (\text{grad} \psi)_j A_k + \psi \cdot \epsilon_{ijk} \partial_j A_k \\ &= \text{grad} \psi \wedge \vec{A} + \psi \cdot \text{rot} \vec{A} \end{aligned}$$

$$\cdot \quad \underline{\text{grad}(\vec{A} \cdot \vec{B})}_i = (\vec{A} \cdot \nabla) B_i + (\vec{B} \cdot \nabla) A_i + \vec{A} \wedge \text{rot} B_i + \vec{B} \wedge \text{rot} A_i = *$$

$$(*)_i = \underbrace{A_j \partial_j B_i + B_j \partial_j A_i + \epsilon_{ijk} A_j (\text{rot} B)_k + \epsilon_{ijk} B_j (\text{rot} A)_k}$$

$$= \dots + \epsilon_{ijk} A_j \epsilon_{kmn} \partial_m B_n + \epsilon_{ijk} B_j \epsilon_{kmn} \partial_m A_n$$

$$= \dots + A_j \epsilon_{kij} \epsilon_{kmn} \partial_m B_n + B_j \epsilon_{kij} \epsilon_{kmn} \partial_m A_n$$

$$= \dots + A_j (\delta_{im} \delta_{jn} - \delta_{jm} \delta_{in}) \partial_m B_n + B_j (\delta_{im} \delta_{jn} - \delta_{jm} \delta_{in}) \partial_m A_n$$

$$= \dots + A_j \delta_{jn} \partial_i B_n - A_j \delta_{in} \partial_j B_n + B_j \delta_{jn} \partial_i A_n - B_j \delta_{in} \partial_j A_n$$

$$= \dots + A_j \partial_i B_j - A_j \partial_j B_i + B_j \partial_i A_j - B_j \partial_j A_i$$

$$= A_j \partial_i B_j + B_j \partial_i A_j = \partial_i (A_j B_j) = \text{grad}(\vec{A} \cdot \vec{B})_i$$

$$\cdot \quad \underline{\text{div}(\vec{A} \wedge \vec{B})} = \partial_i (\epsilon_{ijk} A_j B_k) = \epsilon_{ijk} (\partial_i A_j) B_k + \epsilon_{ijk} A_j \partial_i B_k$$

$$= B_k \epsilon_{kij} \partial_i A_j - A_j \epsilon_{jik} \partial_i B_k = \vec{B} \text{rot} \vec{A} - \vec{A} \text{rot} \vec{B}$$

Dirac'sche Delta-Funktion 1.2

$$a) \cdot \rho(r, \varphi, z) = \frac{Q}{4\pi R^2} \delta(r-R)$$

$$\begin{aligned} \Rightarrow \text{Ladung} &= \int_{\mathbb{R}^3} \rho \, d\vec{x} = \frac{Q}{4\pi R^2} \cdot \underbrace{4\pi \int_0^{\infty} r^2 \delta(r-R) \, dr}_{= R^2} \\ &= Q \end{aligned}$$

$$b) \cdot \rho(r, \varphi, z) = \frac{\lambda}{2\pi b} \delta(r-b)$$

$$\Rightarrow \frac{\text{Ladung}}{\text{Länge}} = \int_{\mathbb{R}^2} \rho \, d\vec{x} = \frac{\lambda}{2\pi b} \cdot 2\pi \int_0^{\infty} r \delta(r-b) \, dr = \lambda$$